

A1 having a variable booster characteristic. Variation of the characteristic may be effected for example by switching between at least two predetermined characteristics of braking force as a function of brake pedal force.

Amend Paragraph [0023] as follows:

Sub ch [0023] (Amended) A first example of a device according to the invention, shown in Figure 1, has a processor 1 for monitoring vehicle dynamic conditions and detecting a condition of vehicle instability. Processor 1 receives signals from detectors, such as steering wheel angle W_L , rotational wheel speed n_R , yaw rate G_R and transverse acceleration \dot{V}_{quer} , and provides an output signal A1, which may be provided to an Electronic Stability (ESP) control unit 8, for vehicle movement dynamics control, as well as to a brake controller 3. Brake controller 3 operates to control the operation of braking force booster 2, which increases the braking force supplied by the brake pedal 8. Controller 3 provides for variation in the braking force applied to the vehicle wheels as a function of applied brake pedal force.

Amend Paragraph [0029] as follows:

A3 [0029] (Amended) Now if the processor 1 detects an unstable condition respecting the dynamics of vehicle movement, the controller 5 drives the actuator 6 so that the free play of the clamping device 7 is overcome before the brake action is actually produced by the driver of the vehicle, so that the brake is preloaded.